Math 2550 HW 8 Solutions

$$\begin{split} & (I)(\alpha) \\ & T(\frac{x}{y}) = \begin{pmatrix} x + 2y \\ 3x - y \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \\ & So, T(\overline{y}) = A \overline{y} \text{ where } A = \begin{pmatrix} 1 & 2 \\ 3 & -1 \end{pmatrix} \\ \end{split}$$

$$\begin{array}{c} \hline 1 \\ \hline 2 \\ \hline 1 \\ \hline 2 \\ \hline 2$$

$$\begin{split} \hline (f)(c) \\ T\begin{pmatrix} x \\ y \\ z \end{pmatrix} &= \begin{pmatrix} -y \\ x+y+z \\ 2x+z \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 1 & 1 \\ 2 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \\ \hline z \end{pmatrix} \\ So, T(\vec{v}) &= A\vec{v} \text{ where } A = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 1 & 1 \\ z & 0 & 1 \end{pmatrix}$$

Basis for eigenspace  $E_3(A)$  for  $\lambda = 3$ : We must find a basis for all solutions to  $A\vec{x} = 3\vec{x}$ .

Solving:  

$$\begin{pmatrix} 3 & 0 \\ 8 & -1 \end{pmatrix} \begin{pmatrix} 9 \\ 6 \end{pmatrix} = 3 \begin{pmatrix} 9 \\ 6 \end{pmatrix} \\
\begin{pmatrix} 3 & 4 & 0 & 6 \\ 8 & 4 & -6 \end{pmatrix} = \begin{pmatrix} 39 \\ 3b \end{pmatrix} \\
\begin{pmatrix} 0 \\ 8a & -4b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Need to solve:  

$$8a-4b=0$$

$$0=0$$

$$\frac{1}{8}R_{1} \rightarrow R_{1}$$
or equivalently:  

$$a-\frac{1}{2}b=0$$

$$0=0$$

The solutions are:

So,  $\vec{X} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} \frac{1}{2}t \\ t \end{pmatrix} = t \begin{pmatrix} y_2 \\ 1 \end{pmatrix}$ gives all the elements in the eigenspace  $E_3(A)$ . So, a basis for  $E_3(A)$  is  $\begin{pmatrix} y_2 \\ 1 \end{pmatrix}$ 

and dim 
$$(E_3(A)) = 1$$
.  
So,  $\lambda = 3$  has geometric multiplicity 1.  
Basis for eigenspace  $E_{-1}(A)$  for  $\lambda = -1$ :  
We need to solve  $A\vec{x} = -\vec{x}$ .  
Solving:  $\begin{pmatrix} 3 & 0 \\ 8 & -1 \end{pmatrix} \begin{pmatrix} 9 \\ 6 \end{pmatrix} = -\begin{pmatrix} 9 \\ 6 \end{pmatrix}$   
 $\begin{pmatrix} 3a + 0b \\ 8a - b \end{pmatrix} = \begin{pmatrix} -a \\ -b \end{pmatrix}$   
 $\begin{pmatrix} 4a \\ 8a \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ 

So, a basis for E. (A) is 
$$\binom{n}{1}$$
  
and dim  $(E_{-1}(A)) = 1$  and  
the geometric multiplicity of  $A = -1$   
is 1.  
Summary table for  $A = \binom{3 \ 0}{8 \ -1}$   
Eigenvalue  $\lambda$  algebraic basis for geometric  
multiplicity  $E_{\lambda}(A)$  multiplicity  
 $\lambda = 3$  |  $\binom{1}{2}$  | 1  
 $\lambda = -1$  |  $\binom{0}{1}$  | 1

$$3(b) A = \begin{pmatrix} 10 & -9 \\ y & -2 \end{pmatrix}$$
  
characteristic polynomial of A  

$$det (A - \lambda I_{2}) = det \left( \begin{pmatrix} 10 & -9 \\ y & -2 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right)$$

$$= det \begin{pmatrix} 10 - \lambda & -9 \\ y & -2 - \lambda \end{pmatrix}$$

$$= (10 - \lambda)(-2 - \lambda) - (4)(-9)$$

$$= -20 - 10\lambda + 2\lambda + \lambda^{2} + 36$$

$$= \lambda^{2} - 8\lambda + 16$$

$$= (\lambda - 4)^{2}$$
Thus,  $\lambda = 4$  is the unly eigenvalue  
with algebraic multiplicity Z.  
basis for Eq (A) for eigenvalue  $\lambda = 4$   
We must solve  $A\vec{x} = 4\vec{x}$ .  
Solving:  $\begin{pmatrix} 10 -9 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 4 \begin{pmatrix} a \\ b \end{pmatrix}$   
 $\begin{pmatrix} 10a - 9b \\ 4a - 2b \end{pmatrix} = \begin{pmatrix} 4a \\ 4b \end{pmatrix}$ 

$$\begin{pmatrix} 6a - 9b \\ 4a - 6b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

We must solve  

$$\begin{bmatrix}
6a - 9b = 0 \\
4a - 6b = 0
\end{bmatrix}$$

We have  

$$\begin{pmatrix} 6 & -9 & | & 0 \\ 4 & -6 & | & 0 \end{pmatrix} \xrightarrow{\frac{1}{6}R_1 \to R_1} \begin{pmatrix} 1 & -3/2 & | & 0 \\ 4 & -6 & | & 0 \end{pmatrix}$$
  
 $-4R_1 + R_2 \to R_2 \begin{pmatrix} 1 & -3/2 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix}$ 

We get:

$$\begin{array}{c} \alpha - \frac{3}{2}b = 0 \\ 0 = 0 \end{array}$$
 leading: a free : b

So, 
$$b = t$$
  
 $a = \frac{3}{2}b = \frac{3}{2}t$   
Thus, all the elements of Ey(A) are  
of the form  
 $\vec{x} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 3/2 & t \\ t \end{pmatrix} = t \begin{pmatrix} 3/2 \\ l \end{pmatrix}$ 

Thus, a basis for Eq(A) is 
$$\binom{3/2}{1}$$
  
So, dim (Eq(A)) = | and the  
geometric multiplicity of  $\lambda$ =4 is 1.  
Summary table for A:  
 $\frac{1}{2} \frac{1}{2} \frac{1}{2$ 

$$\widehat{\mathbf{G}}(c) \quad A = \begin{pmatrix} s & o \\ o & s \end{pmatrix}$$

$$characteristic p.lynomial of A$$

$$det(A - \lambda I_{2}) = det\left(\begin{pmatrix} s & o \\ o & s \end{pmatrix} - \lambda \begin{pmatrix} l & 0 \\ o & 1 \end{pmatrix}\right)$$

$$= det\begin{pmatrix} s - \lambda & 0 \\ 0 & 5 - \lambda \end{pmatrix}$$

$$= (5 - \lambda)(5 - \lambda) - (o)(o)$$

$$= (5 - \lambda)(5 - \lambda) - (o)(o)$$

$$= (5 - \lambda)(5 - \lambda) - (o)(o)$$

$$= (\lambda - 5)(\lambda - 5) \leftarrow I \text{ for each the only form each the two (-1)} s$$

$$= (\lambda - 5)^{2} \qquad \text{cancelled out}$$
Thus,  $\lambda = 5$  is the only eigenvalue of A and it has algebraic multiplicity Z.  
basis for  $E_{s}(A)$  for  $\lambda = 5$ :  
We need to solve  $A \overrightarrow{x} = 5 \overrightarrow{x}$ 

Solving: 
$$\begin{pmatrix} 5 & 0 \\ 0 & 5 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 5 \begin{pmatrix} a \\ b \end{pmatrix}$$
  
 $\begin{pmatrix} 5a + 0b \\ 0a + 5b \end{pmatrix} = \begin{pmatrix} 5a \\ 5b \end{pmatrix}$   
 $\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ 

We get  

$$0 = 0$$
  $\leftarrow$  no leading variables  
 $0 = 0$   $\leftarrow$  a,b are both free!

Solutions are:  

$$a = t$$
  
 $b = u$   
Thus, all elements of  $E_s(A)$  are of  
the form  
 $\vec{x} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} t \\ u \end{pmatrix} = \begin{pmatrix} t \\ c \end{pmatrix} + \begin{pmatrix} 0 \\ u \end{pmatrix} = t \begin{pmatrix} 1 \\ 0 \end{pmatrix} + u \begin{pmatrix} 0 \\ 1 \end{pmatrix}$   
Thus,  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$  span  $E_s(A)$  and since  
they are linearly independent (it's the

standard basis) they form a basis  
for 
$$E_5(A)$$
.  
Thus, dim  $(E_5(A)) = 2$  and the  
geometric multiplicity of  $\lambda = 5$  is 2.  
Summary tuble for  $A = \begin{pmatrix} 5 & 0 \\ 0 & 5 \end{pmatrix}$   
eigenvalue  $\lambda$  algebraic basis for geometric  
multiplicity  $E_{\lambda}(A)$  multiplicity  
 $\lambda = 5$  2  $\binom{1}{0}, \binom{0}{1}$  2

The only eigenvalue is 
$$\lambda = 0$$
 and  
it has algebraic multiplicity 3.  
basis for  $E_0(A)$  for  $\lambda = 0$ :  
Solving:  $A\vec{x} = 0 \cdot \vec{x}$   
 $\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ b \\ c \end{pmatrix} = 0 \begin{pmatrix} 0 \\ b \\ c \end{pmatrix}$   
 $\begin{pmatrix} b \\ c \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ c \end{pmatrix}$ 

giving:  

$$b = 0$$
 leading: b, c  
 $c = 0$  free: c  
 $o = 0$ 

This gives  

$$a + c = 0$$
 leading: a  
 $0 = 0$  free: b, c  
 $0 = 0$ 

Solutions:  

$$b = t$$

$$c = u$$

$$a = -c = -u$$
Thus, every  $\vec{x}$  in  $E_3(A)$  is of the form  

$$\vec{x} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} -u \\ t \\ u \end{pmatrix} = \begin{pmatrix} 0 \\ t \\ c \end{pmatrix} + \begin{pmatrix} -u \\ 0 \\ u \end{pmatrix}$$

$$= t \begin{pmatrix} 0 \\ t \\ 0 \end{pmatrix} + u \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$
Thus,  $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$  s pan  $E_3(A)$ .  
Since these two vectors are not multiples  
of each other they form a basis

for E<sub>3</sub>(A). Thus, dim (E<sub>3</sub>(A)) = 2  
and 
$$\lambda = 3$$
 has geometric multiplicity 2.  
  
basis for E<sub>5</sub>(A) for  $\lambda = 5$ :  
  
 $\begin{pmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ 1 & 0 & 4 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 5 \begin{pmatrix} a \\ b \\ c \end{pmatrix}$   
 $\begin{pmatrix} 4a & +c \\ 2a+3b+2c \\ a & +4c \end{pmatrix} = \begin{pmatrix} 5a \\ 5b \\ c \end{pmatrix}$   
 $\begin{pmatrix} 4a & +c \\ 2a+3b+2c \\ a & +4c \end{pmatrix} = \begin{pmatrix} 5a \\ 5b \\ 5c \end{pmatrix}$   
 $\begin{pmatrix} -a & +c \\ 2a-2b+2c \\ a & -c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ c \end{pmatrix}$   
  
Need to solve  
 $\begin{pmatrix} -a & +c \\ 2a-2b+2c = 0 \\ a & -c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ c \end{pmatrix}$   
Need to solve  
 $\begin{pmatrix} -a & +c \\ 2a-2b+2c = 0 \\ a & -c = 0 \end{pmatrix}$   
olving:  $\begin{pmatrix} -1 & 0 & 1 & 0 \\ 2 & -2 & 2 & 0 \\ 1 & 0 & -1 & 0 \end{pmatrix} \xrightarrow{-R_1 + R_1} \begin{pmatrix} 1 & 0 & -1 & 0 \\ 2 & -2 & 2 & 0 \\ 1 & 0 & -1 & 0 \end{pmatrix}$ 

$$\begin{array}{c} -2R_{1}+R_{2}+R_{1} \\ \hline \\ \hline \\ -R_{1}+R_{3}+R_{3} \end{array} \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & -2 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{-\frac{1}{2}R_{2}+R_{2}} \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

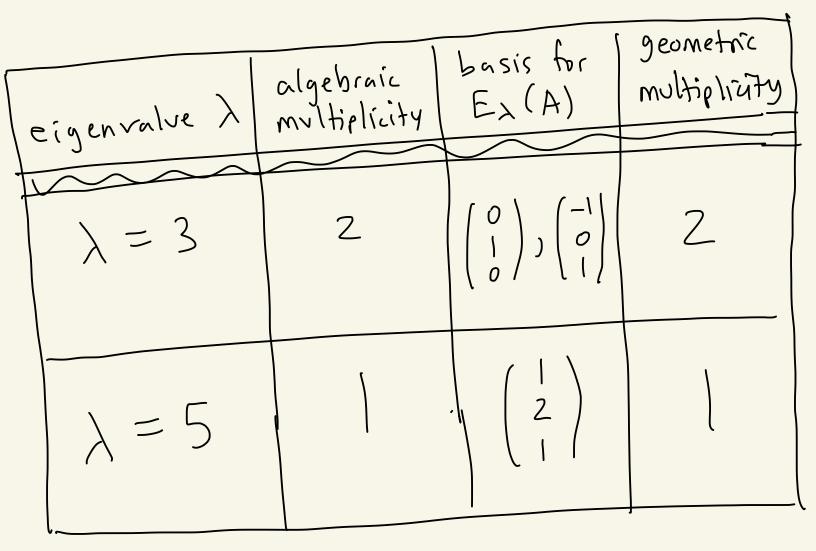
Need to solve:  

$$a -c = 0$$
 leading: a, b  
 $b - 2c = 0$  free: c  
 $v = 0$ 

Solutions are:  

$$c = t$$
  
 $b = 2c = 2t$   
 $a = c = t$   
Thus every  $\vec{x}$  in  $E_s(A)$  is of the form  
 $\vec{x} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} t \\ 2t \\ t \end{pmatrix} = t \begin{pmatrix} 2 \\ 1 \end{pmatrix}$   
Thus,  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  is a basis for  $E_s(A)$   
and dim $(E_s(A)) = 1$  and  
 $\lambda = 5$  has geometric multiplicity 1.

Summary table for 
$$A = \begin{pmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ 1 & 0 & 4 \end{pmatrix}$$



$$(3)(f) \quad A = \begin{pmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix}$$

$$(a)(f) \quad A = \begin{pmatrix} 4 & 0 & 1 \\ -2 & 0 & 1 \\ -2 & 0 & 1 \end{pmatrix}$$

$$(b)(1 - \lambda) = det \begin{pmatrix} 4 - \lambda \\ -2 & 0 \\ -2 & 0 & 1 \end{pmatrix}$$

$$= det \begin{pmatrix} 4 - \lambda \\ -2 \\ -2 & 0 \\ -2 \end{pmatrix} \qquad (col. 2) \qquad (f)(1 - \lambda) + (f$$

Thus, the eigenvalues are 
$$\lambda = 1, 2, 3$$
  
each with algebraic multiplicity 1.

basis for 
$$E_1(A)$$
 for  $\lambda = 1$ :  
Need to solve  $A\vec{x} = 1\cdot\vec{x}$   
Solving:  $\begin{pmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 1\cdot\begin{pmatrix} b \\ c \\ c \end{pmatrix}$   
 $\begin{pmatrix} 4 & a & 1 \\ -2 & 0 \\ -2 & 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 1\cdot\begin{pmatrix} b \\ c \\ c \end{pmatrix}$   
 $\begin{pmatrix} 4 & a & +c \\ -2a & +c \\ -2a & +c \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \\ c \end{pmatrix}$   
 $\begin{pmatrix} 3a & +c \\ -2a & +c \\ -2a & c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ c \end{pmatrix}$ 

This gives:  

$$\begin{array}{cccc}
\alpha & \pm \frac{1}{3}c = 0 & \text{leading: } a, c \\
c = 0 & \text{free: } b \\
0 = 0
\end{array}$$

Solutions:

b=t  
c=0  
a=-1/3c=0  
Thus, all the vectors 
$$\vec{x}$$
 in  $E_1(A)$  are of the  
furn  $\vec{x} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} = t \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ .  
So,  $\begin{pmatrix} 0 \\ b \end{pmatrix}$  is a basis for  $E_1(A)$  and  
dim $(E_1(A)) = 1$  and  $\lambda = 1$  has geometric  
multiplicity 1.  
basis for  $E_2(A)$  for  $\lambda = 2$ .  
Solving:  $A\vec{x} = 2\vec{x}$   
 $\begin{pmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix} \begin{pmatrix} 9 \\ b \\ -2 \end{pmatrix} = 2 \begin{pmatrix} 9 \\ b \\ -2 \end{pmatrix}$ 

$$\begin{pmatrix} 4\alpha + c \\ -2\alpha + b \\ -2\alpha + c \end{pmatrix} = \begin{pmatrix} 2\alpha \\ 2b \\ 2c \end{pmatrix}$$
$$\begin{pmatrix} 2\alpha + c \\ -2\alpha - b \\ -2\alpha - c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Need to solve:  

$$2a + c = 0$$

$$-2a - b = 0$$

$$-2a - c = 0$$

$$S_{0} \{ \forall i \land g : \\ \begin{pmatrix} 2 & 0 & | & 0 \\ -2 & -1 & 0 & 0 \\ -2 & 0 & -1 & 0 & 0 \end{pmatrix} \xrightarrow{R_{1} + R_{2} \to R_{2}} \begin{pmatrix} 2 & 0 & | & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\frac{1}{2} \frac{R_{1} \to R_{1}}{-R_{2} \to R_{2}} \begin{pmatrix} 1 & 0 & \frac{1}{2} & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

We get:  

$$a + \frac{1}{2}c = 0$$
 |eading: a,b  
 $b - c = 0$  free: c  
 $u = 0$ 

Solution: c = t b = c = t $\alpha = -\frac{1}{2}c = -\frac{1}{2}t$ 

Thus all the vectors 
$$\bar{x}$$
 in  $E_2(A)$  are of  
the turn  $\bar{x} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -\frac{1}{2}t \\ t \end{pmatrix} = t \begin{pmatrix} -\frac{1}{2}t \\ t \end{pmatrix}$   
So,  $\begin{pmatrix} -\frac{1}{2}t \\ t \end{pmatrix}$  is a basis for  $E_2(A)$  and  
dim  $(E_2(A)) = 1$  and  $\lambda = 2$  has geometric  
multiplicity 1.  
basis for  $E_3(A)$  for  $\lambda = 3$ :  
Solving:  $A\bar{x} = 3\bar{x}$   
 $\begin{pmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 3 \begin{pmatrix} a \\ b \\ c \end{pmatrix}$   
 $\begin{pmatrix} 4a & tc \\ -2a + bc \\ -2a & +cc \end{pmatrix} = \begin{pmatrix} 3a \\ 3b \\ 3c \end{pmatrix}$   
 $\begin{pmatrix} a & tc \\ -2a - 2b \\ -2a & -2c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$   
Need to solve  
 $\begin{bmatrix} -a & -2b \\ -2a & -2c \\ -2a \\ -2a & -2c \\ -2a \\ -$ 

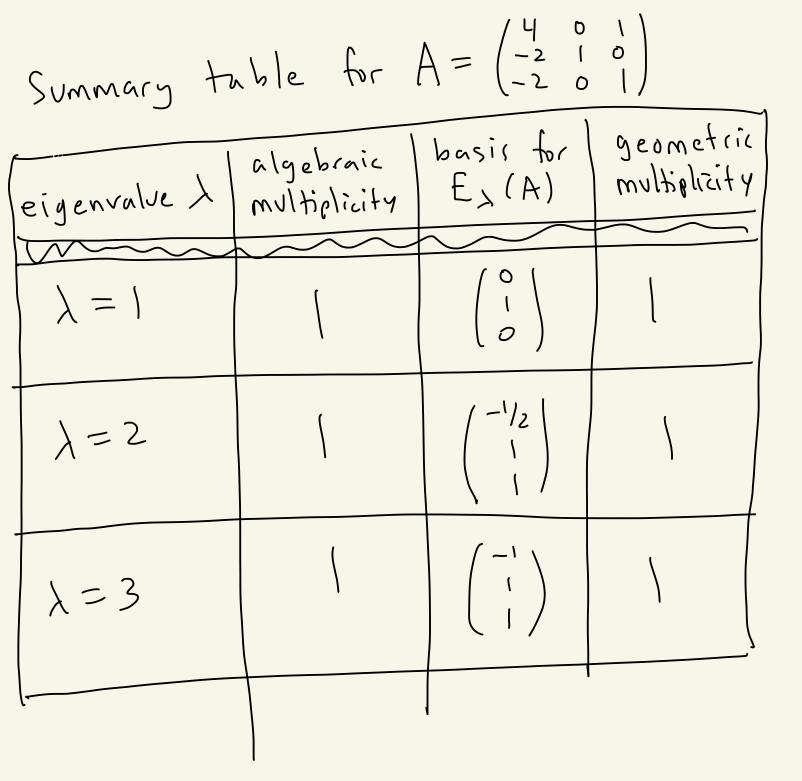
$$\begin{aligned}
S_{s} \text{Uing:} \\
\begin{pmatrix} 1 & 0 & 1 & 0 \\ -2 & -2 & 0 & 0 \\ -2 & 0 & -2 & 0 \end{pmatrix} \xrightarrow{2R_{1}+R_{2} \rightarrow R_{2}} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & -2 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\
\xrightarrow{-\frac{1}{2}R_{2} \rightarrow R_{2}} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}
\end{aligned}$$

This gives:

$$\begin{array}{ccc} a & +c = 0 \\ b - c = 0 \\ 0 = 0 \end{array}$$
 leading: a, b

Solution is  

$$c = t$$
  
 $b = c = t$   
 $\alpha = -c = -t$ 



9) Suppose 
$$\vec{x}$$
 is an eigenvalue of  
A with eigenvalue  $\lambda$ .  
Then,  $A\vec{x} = \lambda\vec{x}$ .  
So,  $A^2\vec{x} = A(A\vec{x}) = A(\lambda\vec{x})$   
 $= \lambda(A\vec{x})$   
 $= \lambda\cdot\lambda\vec{x}$   
 $= \lambda^2\vec{x}$ .  
And,  $A^2\vec{x} = A(A^2\vec{x}) = A(\lambda^2\vec{x})$   
 $= \lambda^2(A\vec{x})$   
 $= \lambda^2(\lambda\vec{x})$   
 $= \lambda^2(\lambda\vec{x})$   
 $= \lambda^2(\lambda\vec{x})$   
 $= \lambda^2\vec{x}$ .  
Carry on in this fashion we will  
get that  $A^n\vec{x} = \lambda^n\vec{x}$   
for  $n = 1, 2, 3, 4$ ...